

## 球座標系におけるテンソル

<デカルト座標系 $(x, y, z)$ と球座標系 $(r, \theta, \phi)$ >

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases} \quad \begin{cases} 0 \leq r \leq +\infty \\ 0 \leq \theta \leq \pi \\ 0 \leq \phi \leq 2\pi \end{cases} \quad (1)$$

$$r = \sqrt{x^2 + y^2 + z^2}, \quad \theta = \tan^{-1} \left( \frac{\sqrt{x^2 + y^2}}{z} \right), \quad \phi = \tan^{-1} \left( \frac{y}{x} \right) \quad (2)$$

<単位ベクトル>

$$\begin{cases} \vec{e}_r = (\sin \theta \cos \phi) \vec{e}_x + (\sin \theta \sin \phi) \vec{e}_y + (\cos \theta) \vec{e}_z \\ \vec{e}_\theta = (\cos \theta \cos \phi) \vec{e}_x + (\cos \theta \sin \phi) \vec{e}_y + (-\sin \theta) \vec{e}_z \\ \vec{e}_\phi = (-\sin \phi) \vec{e}_x + (\cos \phi) \vec{e}_y + (0) \vec{e}_z \end{cases} \quad (3a)$$

$$\begin{cases} \vec{e}_x = (\sin \theta \cos \phi) \vec{e}_r + (\cos \theta \cos \phi) \vec{e}_\theta + (-\sin \phi) \vec{e}_\phi \\ \vec{e}_y = (\sin \theta \sin \phi) \vec{e}_r + (\cos \theta \sin \phi) \vec{e}_\theta + (\cos \phi) \vec{e}_\phi \\ \vec{e}_z = (\cos \theta) \vec{e}_r + (-\sin \theta) \vec{e}_\theta + (0) \vec{e}_\phi \end{cases} \quad (3b)$$

<単位ベクトルの偏導関数>

$$\begin{cases} \frac{\partial \vec{e}_r}{\partial r} = \vec{0}, & \frac{\partial \vec{e}_\theta}{\partial r} = \vec{0}, & \frac{\partial \vec{e}_\phi}{\partial r} = \vec{0} \\ \frac{\partial \vec{e}_r}{\partial \theta} = \vec{e}_\theta, & \frac{\partial \vec{e}_\theta}{\partial \theta} = -\vec{e}_r, & \frac{\partial \vec{e}_\phi}{\partial \theta} = \vec{0} \\ \frac{\partial \vec{e}_r}{\partial \phi} = (\sin \theta) \vec{e}_\phi, & \frac{\partial \vec{e}_\theta}{\partial \phi} = (\cos \theta) \vec{e}_\phi, & \frac{\partial \vec{e}_\phi}{\partial \phi} = (-\sin \theta) \vec{e}_r + (-\cos \theta) \vec{e}_\theta \end{cases} \quad (4)$$

<位置ベクトル>

$$\begin{aligned} \vec{r} = r \vec{e}_r \quad \Rightarrow \quad d\vec{r} &= (dr) \vec{e}_r + r (d\vec{e}_r) = (dr) \vec{e}_r + r \left( \frac{\partial \vec{e}_r}{\partial r} dr + \underbrace{\frac{\partial \vec{e}_r}{\partial \theta}}_{\vec{e}_\theta} d\theta + \underbrace{\frac{\partial \vec{e}_r}{\partial \phi}}_{(\sin \theta) \vec{e}_\phi} d\phi \right) \\ &= (dr) \vec{e}_r + (rd\theta) \vec{e}_\theta + (r \sin \theta d\phi) \vec{e}_\phi \end{aligned} \quad (5)$$

以下、式(4)に注意しながら演算を進める。

<勾配>

$$\vec{\nabla} = \vec{e}_x \frac{\partial}{\partial x} + \vec{e}_y \frac{\partial}{\partial y} + \vec{e}_z \frac{\partial}{\partial z} = \vec{e}_r \frac{\partial}{\partial r} + \frac{\vec{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\vec{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \quad (6)$$

<ラプラシアン>

$$\begin{aligned}
\nabla^2 &= \vec{\nabla} \cdot \vec{\nabla} = \left( \vec{e}_r \frac{\partial}{\partial r} + \frac{\vec{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\vec{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \cdot \left( \vec{e}_r \frac{\partial}{\partial r} + \frac{\vec{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\vec{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \\
&= \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2}
\end{aligned} \tag{7}$$

<ベクトル場の発散>

$$\begin{aligned}
\vec{\nabla} \cdot \vec{u} &= \left( \vec{e}_r \frac{\partial}{\partial r} + \frac{\vec{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\vec{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \cdot (\vec{e}_r u_r + \vec{e}_\theta u_\theta + \vec{e}_\phi u_\phi) \\
&= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (u_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi}
\end{aligned} \tag{8}$$

<実質微分>

$$\begin{aligned}
\frac{D}{Dt} &= \frac{\partial}{\partial t} + \vec{u} \cdot \vec{\nabla} = \frac{\partial}{\partial t} + (\vec{e}_r u_r + \vec{e}_\theta u_\theta + \vec{e}_\phi u_\phi) \cdot \left( \vec{e}_r \frac{\partial}{\partial r} + \frac{\vec{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\vec{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \\
&= \frac{\partial}{\partial t} + u_r \frac{\partial}{\partial r} + \frac{u_\theta}{r} \frac{\partial}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial}{\partial \phi}
\end{aligned} \tag{9}$$

<ベクトル場の実質微分>

式(9)の結果を用いる.

$$\begin{aligned}
\frac{D\vec{b}}{Dt} &= \frac{\partial \vec{b}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{b} = \left( \frac{\partial}{\partial t} + u_r \frac{\partial}{\partial r} + \frac{u_\theta}{r} \frac{\partial}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) (\vec{e}_r b_r + \vec{e}_\theta b_\theta + \vec{e}_\phi b_\phi) \\
&= \vec{e}_r \left( \frac{\partial b_r}{\partial t} + u_r \frac{\partial b_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial b_r}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial b_r}{\partial \phi} - \frac{u_\theta b_\theta + u_\phi b_\phi}{r} \right) \\
&\quad + \vec{e}_\theta \left( \frac{\partial b_\theta}{\partial t} + u_r \frac{\partial b_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial b_\theta}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial b_\theta}{\partial \phi} + \frac{u_\theta b_r}{r} - \frac{u_\phi b_\phi}{r} \cot \theta \right) \\
&\quad + \vec{e}_\phi \left( \frac{\partial b_\phi}{\partial t} + u_r \frac{\partial b_\phi}{\partial r} + \frac{u_\theta}{r} \frac{\partial b_\phi}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial b_\phi}{\partial \phi} + \frac{u_\phi b_r}{r} + \frac{u_\theta b_\theta}{r} \cot \theta \right)
\end{aligned} \tag{10}$$

<ベクトル場の回転>

$$\begin{aligned}
\bar{\nabla} \times \bar{u} &= \left( \bar{e}_r \frac{\partial}{\partial r} + \frac{\bar{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\bar{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) (\bar{e}_r u_r + \bar{e}_\theta u_\theta + \bar{e}_\phi u_\phi) \\
&= \bar{e}_r \left\{ \frac{1}{r \sin \theta} \frac{\partial (u_\phi \sin \theta)}{\partial \theta} - \frac{1}{r \sin \theta} \frac{\partial (u_\theta)}{\partial \phi} \right\} + \bar{e}_\theta \left\{ \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{1}{r} \frac{\partial (r u_\phi)}{\partial r} \right\} + \bar{e}_\phi \left\{ \frac{1}{r} \frac{\partial (r u_\theta)}{\partial r} - \frac{1}{r} \frac{\partial u_r}{\partial \theta} \right\} \\
&= \frac{\bar{e}_r}{r^2 \sin \theta} \left\{ \frac{\partial (r u_\phi \sin \theta)}{\partial \theta} - \frac{\partial (r u_\theta)}{\partial \phi} \right\} + \frac{\bar{e}_\theta}{r \sin \theta} \left\{ \frac{\partial u_r}{\partial \phi} - \frac{\partial (r u_\phi \sin \theta)}{\partial r} \right\} + \frac{\bar{e}_\phi}{r} \left\{ \frac{\partial (r u_\theta)}{\partial r} - \frac{\partial u_r}{\partial \theta} \right\} \\
&= \begin{vmatrix} \frac{\bar{e}_r}{r^2 \sin \theta} & \frac{\bar{e}_\theta}{r \sin \theta} & \frac{\bar{e}_\phi}{r} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ u_r & r u_\theta & r u_\phi \sin \theta \end{vmatrix}
\end{aligned} \tag{11}$$

<ベクトル場の勾配>

$$\begin{aligned}
\bar{\nabla} \bar{u} &= \left( \bar{e}_r \frac{\partial}{\partial r} + \frac{\bar{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\bar{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) (\bar{e}_r u_r + \bar{e}_\theta u_\theta + \bar{e}_\phi u_\phi) \\
&= \bar{e}_r \bar{e}_r \frac{\partial u_r}{\partial r} + \bar{e}_r \bar{e}_\theta \frac{\partial u_\theta}{\partial r} + \bar{e}_r \bar{e}_\phi \frac{\partial u_\phi}{\partial r} \\
&\quad + \bar{e}_\theta \bar{e}_r \left( \frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} \right) + \bar{e}_\theta \bar{e}_\theta \left( \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) + \bar{e}_\theta \bar{e}_\phi \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} \right) \\
&\quad + \bar{e}_\phi \bar{e}_r \left( \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} \right) + \bar{e}_\phi \bar{e}_\theta \left( \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi \cot \theta}{r} \right) + \bar{e}_\phi \bar{e}_\phi \left( \frac{u_r}{r} + \frac{u_\theta \cos \theta}{r \sin \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right)
\end{aligned} \tag{12}$$

<ベクトル場のラプラシアン>

式(12)の発散をとる.

$$\begin{aligned}
\nabla^2 \bar{u} &= \bar{\nabla} \cdot (\bar{\nabla} \bar{u}) = \left( \bar{e}_r \frac{\partial}{\partial r} + \frac{\bar{e}_\theta}{r} \frac{\partial}{\partial \theta} + \frac{\bar{e}_\phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \\
&\quad \cdot \left( \begin{aligned} &\bar{e}_r \bar{e}_r \frac{\partial u_r}{\partial r} + \bar{e}_r \bar{e}_\theta \frac{\partial u_\theta}{\partial r} + \bar{e}_r \bar{e}_\phi \frac{\partial u_\phi}{\partial r} + \bar{e}_\theta \bar{e}_r \left( \frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} \right) + \bar{e}_\theta \bar{e}_\theta \left( \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) + \bar{e}_\theta \bar{e}_\phi \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} \right) \\ &+ \bar{e}_\phi \bar{e}_r \left( \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} \right) + \bar{e}_\phi \bar{e}_\theta \left( \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi \cot \theta}{r} \right) + \bar{e}_\phi \bar{e}_\phi \left( \frac{u_r}{r} + \frac{u_\theta \cos \theta}{r \sin \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \end{aligned} \right)
\end{aligned}$$

$$\begin{aligned}
&= \bar{e}_r \left( \underbrace{\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial u_r}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial u_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_r}{\partial \phi^2}}_{\nabla^2 u_r} - \frac{2u_r}{r^2} - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta} - \frac{2u_\theta \cot \theta}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \\
&+ \bar{e}_\theta \left( \underbrace{\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial u_\theta}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial u_\theta}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\theta}{\partial \phi^2}}_{\nabla^2 u_\theta} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} \right) \\
&+ \bar{e}_\phi \left( \underbrace{\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial u_\phi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial u_\phi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\phi}{\partial \phi^2}}_{\nabla^2 u_\phi} - \frac{u_\phi}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi} \right)
\end{aligned} \tag{13}$$

<ベクトル場の実質微分 (その2) >

式(12)の結果を使う。

$$\begin{aligned}
\vec{b} \cdot \nabla \vec{u} &= (\bar{e}_r b_r + \bar{e}_\theta b_\theta + \bar{e}_\phi b_\phi) \\
&\cdot \left( \begin{aligned} &\bar{e}_r \bar{e}_r \frac{\partial u_r}{\partial r} + \bar{e}_r \bar{e}_\theta \frac{\partial u_\theta}{\partial r} + \bar{e}_r \bar{e}_\phi \frac{\partial u_\phi}{\partial r} + \bar{e}_\theta \bar{e}_r \left( \frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} \right) + \bar{e}_\theta \bar{e}_\theta \left( \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) + \bar{e}_\theta \bar{e}_\phi \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} \right) \\ &+ \bar{e}_\phi \bar{e}_r \left( \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} \right) + \bar{e}_\phi \bar{e}_\theta \left( \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi \cot \theta}{r} \right) + \bar{e}_\phi \bar{e}_\phi \left( \frac{u_r}{r} + \frac{u_\theta \cos \theta}{r \sin \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \end{aligned} \right) \\
&= \bar{e}_r b_r \frac{\partial u_r}{\partial r} + \bar{e}_\theta b_r \frac{\partial u_\theta}{\partial r} + \bar{e}_\phi b_r \frac{\partial u_\phi}{\partial r} + \bar{e}_r b_\theta \left( \frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} \right) + \bar{e}_\theta b_\theta \left( \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) + \bar{e}_\phi b_\theta \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} \right) \\
&+ \bar{e}_r b_\phi \left( \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} \right) + \bar{e}_\theta b_\phi \left( \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi \cot \theta}{r} \right) + \bar{e}_\phi b_\phi \left( \frac{u_r}{r} + \frac{u_\theta \cos \theta}{r \sin \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \\
&= \bar{e}_r \left\{ b_r \frac{\partial u_r}{\partial r} + \frac{b_\theta}{r} \frac{\partial u_r}{\partial \theta} - \frac{b_\theta u_\theta}{r} + \frac{b_\phi}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{b_\phi u_\phi}{r} \right\} \\
&+ \bar{e}_\theta \left\{ b_r \frac{\partial u_\theta}{\partial r} + \frac{b_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{b_\theta u_r}{r} + \frac{b_\phi}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{b_\phi u_\phi \cot \theta}{r} \right\} \\
&+ \bar{e}_\phi \left\{ b_r \frac{\partial u_\phi}{\partial r} + \frac{b_\theta}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{b_\theta u_r}{r} + \frac{b_\phi u_\theta \cos \theta}{r \sin \theta} + \frac{b_\phi}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right\}
\end{aligned} \tag{14}$$

これは、式(10)に示される結果と同じ。

<粘性応力テンソル>

式(12)の結果から

$$\begin{aligned}
\frac{\boldsymbol{\tau}}{\mu} = & \bar{e}_r \bar{e}_r \left\{ 2 \left( -\frac{\Theta}{3} + \frac{\partial u_r}{\partial r} \right) \right\} + \bar{e}_r \bar{e}_\theta \left( \frac{\partial u_\theta}{\partial r} + \frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} \right) + \bar{e}_r \bar{e}_\phi \left( \frac{\partial u_\phi}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} \right) \\
& + \bar{e}_\theta \bar{e}_r \left( \frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} + \frac{\partial u_\theta}{\partial r} \right) + \bar{e}_\theta \bar{e}_\theta \left\{ 2 \left( -\frac{\Theta}{3} + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) \right\} + \bar{e}_\theta \bar{e}_\phi \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi \cot \theta}{r} \right) \\
& + \bar{e}_\phi \bar{e}_r \left( \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} + \frac{\partial u_\phi}{\partial r} \right) + \bar{e}_\phi \bar{e}_\theta \left( \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi \cot \theta}{r} + \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} \right) \\
& + \bar{e}_\phi \bar{e}_\phi \left\{ 2 \left( -\frac{\Theta}{3} + \frac{u_r}{r} + \frac{u_\theta \cot \theta}{r} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right) \right\}
\end{aligned} \tag{15}$$

ただし、 $\Theta = \vec{\nabla} \cdot \vec{u} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi}$

以下、電磁流体力学に必要な基礎方程式（成分表示）を示す。

<質量保存式>

$$\frac{\partial \rho}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \rho = -\rho \vec{\nabla} \cdot \vec{u}$$

式(8), (9)を使って、

$$\frac{\partial \rho}{\partial t} + u_r \frac{\partial \rho}{\partial r} + \frac{u_\theta}{r} \frac{\partial \rho}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial \rho}{\partial \phi} = -\rho \left\{ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right\} \tag{16}$$

<運動方程式>

$$\rho \left\{ \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right\} = -\vec{\nabla} p + \mu \nabla^2 \vec{u} + \vec{j} \times \vec{b} + \rho \vec{g}$$

式(10), (13)を使って、

$$\begin{aligned}
\rho \left( \frac{\partial u_r}{\partial t} + u_r \frac{\partial u_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_r}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\theta^2 + u_\phi^2}{r} \right) = & -\frac{\partial p}{\partial r} + (j_\theta b_\phi - j_\phi b_\theta) + \rho g_r \\
& + \mu \left( \nabla^2 u_r - \frac{2u_r}{r^2} - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta} - \frac{2u_\theta \cot \theta}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right)
\end{aligned} \tag{17}$$

$$\begin{aligned}
\rho \left( \frac{\partial u_\theta}{\partial t} + u_r \frac{\partial u_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} + \frac{u_\theta u_r - u_\phi^2 \cot \theta}{r} \right) = & -\frac{1}{r} \frac{\partial p}{\partial \theta} + (j_\phi b_r - j_r b_\phi) + \rho g_\theta \\
& + \mu \left( \nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} \right)
\end{aligned} \tag{18}$$

$$\begin{aligned}
\rho \left( \frac{\partial u_\phi}{\partial t} + u_r \frac{\partial u_\phi}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{u_\phi u_r}{r} + \frac{u_\phi u_\theta \cot \theta}{r} \right) = & -\frac{1}{r \sin \theta} \frac{\partial p}{\partial \phi} + (j_r b_\theta - j_\theta b_r) + \rho g_\phi \\
& + \mu \left( \nabla^2 u_\phi - \frac{u_\phi}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi} \right)
\end{aligned} \tag{19}$$

<エネルギー方程式>

$$\frac{DT}{Dt} = \alpha \nabla^2 T + \Phi$$

式(7), (9), (15)を使って,

$$\begin{aligned} \frac{\partial T}{\partial t} + u_r \frac{\partial T}{\partial r} + \frac{u_\theta}{r} \frac{\partial T}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial T}{\partial \phi} = \alpha \left\{ \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 T}{\partial \phi^2} \right\} \\ + \mu \left[ \begin{aligned} & 2 \left( \frac{\partial u_r}{\partial r} \right)^2 + 2 \left( \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right)^2 + 2 \left( \frac{u_r}{r} + \frac{u_\theta \cot \theta}{r} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right)^2 \\ & + \left( \frac{\partial u_\theta}{\partial r} + \frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} \right)^2 + \left( \frac{\partial u_\phi}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} \right)^2 + \left( \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi \cot \theta}{r} \right)^2 \\ & - \frac{2}{3} \left\{ \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 u_r \right) + \frac{1}{r \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right\}^2 \end{aligned} \right] \quad (20) \end{aligned}$$

<電荷保存則>

$$\vec{\nabla} \cdot \vec{j} = 0$$

式(8)から

$$\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 j_r) + \frac{1}{r \sin \theta} \frac{\partial (j_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial j_\phi}{\partial \phi} = 0 \quad (21)$$

<Ohmの法則>

$$\vec{j} = \sigma \left( -\vec{\nabla} \varphi - \frac{\partial \vec{a}}{\partial t} + \vec{u} \times \vec{b} \right)$$

式(6)から

$$\begin{aligned} \vec{j} = \sigma \left( \underbrace{-\frac{\partial \varphi}{\partial r} - \frac{\partial a_r}{\partial t} + u_\theta b_\phi - u_\phi b_\theta}_{j_r} \right) \vec{e}_r + \sigma \left( \underbrace{-\frac{1}{r} \frac{\partial \varphi}{\partial \theta} - \frac{\partial a_\theta}{\partial t} + u_\phi b_r - u_r b_\phi}_{j_\theta} \right) \vec{e}_\theta \\ + \sigma \left( \underbrace{-\frac{1}{r \sin \theta} \frac{\partial \varphi}{\partial \phi} - \frac{\partial a_\phi}{\partial t} + u_r b_\theta - u_\theta b_r}_{j_\phi} \right) \vec{e}_\phi \quad (22) \end{aligned}$$

<誘導方程式>

$$\frac{\partial \vec{b}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{b} = (\vec{b} \cdot \vec{\nabla}) \vec{u} + \nu_m \nabla^2 \vec{b}$$

式(10), (13), (14)を使って

$$\begin{aligned} \frac{\partial b_r}{\partial t} + u_r \frac{\partial b_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial b_r}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial b_r}{\partial \phi} = b_r \frac{\partial u_r}{\partial r} + \frac{b_\theta}{r} \frac{\partial u_r}{\partial \theta} + \frac{b_\phi}{r \sin \theta} \frac{\partial u_r}{\partial \phi} \\ + \nu_m \left( \nabla^2 b_r - \frac{2b_r}{r^2} - \frac{2}{r^2} \frac{\partial b_\theta}{\partial \theta} - \frac{2b_\theta \cot \theta}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial b_\phi}{\partial \phi} \right) \quad (23) \end{aligned}$$

$$\begin{aligned} \frac{\partial b_\theta}{\partial t} + u_r \frac{\partial b_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial b_\theta}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial b_\theta}{\partial \phi} + \frac{u_\theta b_r}{r} = b_r \frac{\partial u_\theta}{\partial r} + \frac{b_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{b_\phi}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} + \frac{b_\theta u_r}{r} \\ + v_m \left( \nabla^2 b_\theta + \frac{2}{r^2} \frac{\partial b_r}{\partial \theta} - \frac{b_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial b_\phi}{\partial \phi} \right) \end{aligned} \quad (24)$$

$$\begin{aligned} \frac{\partial b_\phi}{\partial t} + u_r \frac{\partial b_\phi}{\partial r} + \frac{u_\theta}{r} \frac{\partial b_\phi}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial b_\phi}{\partial \phi} + \frac{u_\phi b_r}{r} + \frac{u_\theta b_\theta \cot \theta}{r} = b_r \frac{\partial u_\phi}{\partial r} + \frac{b_\theta}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{b_\phi}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} \\ + \frac{b_\phi u_r}{r} + \frac{b_\phi u_\theta \cot \theta}{r} + v_m \left( \nabla^2 b_\phi - \frac{b_\phi}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin \theta} \frac{\partial b_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial b_\theta}{\partial \phi} \right) \end{aligned} \quad (25)$$

#### 参考文献

- (1) 平野 博之 著「第3版 流れの数値計算と可視化」(丸善株式会社)
- (2) 上野 和之 著「ベクトル解析 道具と考えていねいに」(共立出版)